Differentially Private Release of Synthetic Graphs

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Joint work with Michael Kapralov, Janardhan Kulkarni, Yin Tat Lee



Eliáš, Kapralov, Kulkarni, Lee: Differentially Private Release of Synthetic Graphs

Private network analysis



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Social networks:

- contain valuable information about our societies
- stability of the society, information spread

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Network analysis in a private manner?

A synthetic graph approximating all cuts

Input:

• graph G(V, E) with edge-weights w

- differentially private graph G' with weights w'
- ▶ for any I, $J \subset V$: $w'(I, J) \approx w(I, J)$
 - ▶ i.e., preserving weight of (I, J)-cuts

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Edge-level privacy:

neighboring graphs differ by a single edge

Known results

Randomized response

- ▶ Gupta, Roth, Ullman'12
- $w'_e = w_e + \zeta_e$, where $\zeta_e \sim \text{Lap}(1/\epsilon)$ i.i.d.
- additive error: $O(n^{3/2})$
- \blacktriangleright useful only for graphs with $\gg n^{3/2}$ edges



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Other results

▶ Blocki, Blum, Datta, Sheffet '12; Upadhyay '13

Exponential mechanism: Naïve version

- ▶ score $\Theta(\exp(n^2))$ possible output graphs by their error
- return a sample from this distribution
- error proportional to n^2

¹Only for cuts of type $(S, V \setminus S)$

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- fundamental result: existence of sparsifiers
 - preserve cut sizes¹ with a small multiplicative error
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- fundamental result: existence of sparsifiers
 - preserve cut sizes¹ with a small multiplicative error
 - number of edges: O(n)
 - only exp(O(n log n)) possible sparsifiers!
- \blacktriangleright additive error: $n \log n$, multiplicative error due to sparsification
- Drawback: exponential time!

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Input:

• graph G* s.t.
$$\sum_e w_e^* = \mathfrak{m}$$

- (ε, δ) -DP synthetic graph G with weights w
- with probability (1γ) :
 - ▶ for all I, J ⊂ V: $|w(I, J) w^*(I, J)| \leq \tilde{O}(\sqrt{mn})$
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Lower bounds for purely additive error

 $\Omega(\sqrt{mn/\epsilon})$

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- sample edges by their effective resistance
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Problem:

- only existing edges are sampled
- edge e in the output $\Rightarrow e$ was present in the input!

not private

Find cut approximator using convex optimization

- mirror descent
- iterative technique
- we can choose target precision

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Bound the total privacy

Advanced composition theorem

Convex objective

- ▶ input graph G^* : weights w^* , adjacency matrix A^*
- current solution G: weights w, adjacency matrix A

► let
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Grothendieck problem:

$$F(D) = \max \left\{ \begin{array}{cc} 0 & D \\ D & 0 \end{array} \right) \bullet X; \quad X \text{ is symmetric, } X \succeq 0, X_{\texttt{ii}} = 1 \; \forall \texttt{i} \right\}$$

▶ constant-factor approximation of $\max_{I,J \subset V} |w(I,J) - w^*(I,J)|$

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Properties:

$$\blacktriangleright \nabla F(D) = X^*$$



Optimization problem:

$$\min\left\{F(A(w) - A^*); \sum_{e} w_e = m\right\}$$

- minimization of convex function
- ▶ bounded gradient: $(\nabla F(D))_{i,j} \in [-1, 1]$

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Mirror descent theorem:

• after
$$T = m/n$$
 iterations:

$$F(A(w) - A^*) \leq \tilde{O}(\sqrt{mn})$$

Stochastic gradient

Stochastic gradient: JL transform

- ► release $X^{1/2}\zeta$, where $\zeta \sim N(0, I)$
- stochastic gradient: $S_X = X^{1/2} \zeta \zeta^T X^{1/2}$





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Privacy of the gradient at iteration t:

$$X = \nabla F(A(w^{(t)}) - A^*) \text{ and } \tilde{X} = \nabla F(A(w^{(t)}) - \tilde{A}^*)$$

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$$X^{1/2}\zeta \text{ and } \tilde{X}^{1/2}\zeta \text{ have similar distribution:}$$

$$\mathsf{pdf}_X(x) \leqslant e^{\epsilon_0} \cdot \mathsf{pdf}_{\tilde{X}}(x) \text{ w.p. } (1-\delta_0)$$

$$\varepsilon_0 = O(\log \frac{1}{\delta_0}) \cdot \sqrt{\operatorname{tr} X^{-1}(\tilde{X} - X) X^{-1}(\tilde{X} - X)}$$

► this implies (ϵ_0, δ_0) -DP

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Claim:

▶ If A^* and \tilde{A}^* differ in a single edge, then

$$\sqrt{\operatorname{tr} \mathsf{X}^{-1}(\tilde{\mathsf{X}}-\mathsf{X})\mathsf{X}^{-1}(\tilde{\mathsf{X}}-\mathsf{X})} \leqslant \mathrm{O}(1/\lambda)$$

• crucial property of Ψ : $D^2\Psi(X)[E, E] = -\lambda \operatorname{tr} X^{-1}EX^{-1}E$

Summing up

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► we choose

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• using T = m/n iterations of mirror descent

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- privacy (by Advanced composition thm): $\frac{1}{\lambda}\sqrt{T} = \epsilon$
- error due to low number of iterations: $\tilde{O}(\sqrt{mn})$
- error due to regularization: $\lambda n \log n \leq \tilde{O}(\epsilon^{-1} \sqrt{mn})$

Open problems

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Is our result implementable?

using some convex optimization tool

Questions?





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